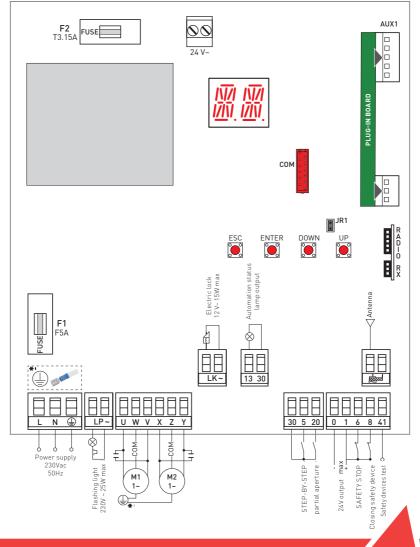


IP2368EN • 2020-07-15 Ditec LCA70

Control panel installation manual for automations with one or two 230V~ motors

(translation of the original instructions)



Contents

		Subject	Page
1.		General safety precautions	3
	1.1	Safety functions	4
2.		EC Declaration of Conformity	4
3.		Technical specifications	4
	3.1	Applications	5
4.		Installation and electrical connections	5
	4.1	Maintenance	7
	4.2	Standard installation	7
		Standard installation wiring diagram	8
5.		Commands and safety devices	8
	5.1	Command inputs	9
		Safety inputs	9
6.		Outputs and accessories	9
7.		Jumper setting	10
8.		Application examples	11
υ.	8.1	Automations with two swinging gates	11
		Automations with one swinging gate	11
9.	0.2	Using menus	12
7.	0 1	Switching the display on and off	12
		Navigation keys	12
		Menu map	12
10	9.3		
10.	10.1	Setting up product for first use	15
		WZ configuration wizard menu	15
-		Basic example of start-up	17
		Frequently used menu sequences	18
		Enabling configurations	18
_		Adding remote controls	18
	10.3.3	Configuring the NC contact safety devices	18
11.		Configuration and settings menu	18
-		Main menu	18
		Second level menu - AT (Automatic Configurations)	19
-		Second level menu - BC (Basic Configurations)	20
		Additional BC level parameters that can be configured (available with AT \rightarrow AA enabled)	21
		Second level menu - BA (Basic Adjustment)	21
		Additional BA level parameters that can be configured (available with $AT \rightarrow AA$ enabled)	25
		Second level menu - RO (Radio Operations) Additional RO level parameters that can be configured (available with $AT \rightarrow AA$ enabled)	25
		Second level menu - SF (Special Functions) Ad enabled	26
		Additional SF level parameters that can be configured (available with AT \rightarrow AA enabled)	27
		Second level menu - CC (Cycle Counter)	20
		Additional CC level parameters that can be configured (available with AT \rightarrow AA enabled)	29
		Level two AP menu (Advanced parameters)	30
		Additional configurable AP level parameters available with AT \rightarrow AA enabled	31
12.		Diagnostics	33
	12.1	Data Logging integrated in the board	33
		Alarm counters	33
		Alarm log	33
13.		Signals visualised on the display	34
	13.1	Display of automation status	34
		Display of safety devices and commands	35
		Display of alarms and faults	36
14.		Troubleshooting	38

Key

This symbol indicates instructions or notes regarding safety, to which special attention must be paid.
 This symbol indicates useful information for the correct operation of the product.
 Factory settings

1. General safety precautions



Failure to observe the information given in this manual may lead to personal injury or damage to the equipment. Keep these instructions for future reference

This installation manual is intended for qualified personnel only.

Installation, electrical connections and adjustments must be performed in accordance with Good Working Methods and in compliance with the present standards.

This product must only be used for the specific purpose for which it was designed.

Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.

Read the instructions carefully before installing the product. Incorrect installation may cause danger.

The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.

Before installing the product, make sure it is in perfect condition.

Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.

The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the automation.

Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.

Check that there is an adequate residual current circuit breaker and a suitable overcurrent cutout upstream of the electrical installation in accordance with Good Working Methods and with the laws in force.

When requested, connect the automation to an effective earthing system that complies with current safety standards.

During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts.

The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation device declines all responsibility if component parts not compatible with safe and correct operation are fitted.

Only use original spare parts when repairing or replacing products.

1.1 Safety functions

The Ditec LCA70 control panel has the following safety functions:

- obstacle recognition with force limiting.

The maximum response time of the safety functions is 0.5s. The reaction time to a faulty safety function is 0.5s.

The safety functions comply with the standards and performance level indicated below:

EN ISO 13849-1:2015 Category 2 PL=c

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

2. EC Declaration of Conformity

Entrematic Group AB declares that the Ditec LCA70 control panel is compliant with the fundamental requisites and other relevant requirements defined down by the following EC directives:

EMC Directive 2014/30/EU; Low Voltage Directive 2014/35/EU. RoHS Directive 2011/65/EU

Landskrona, 15-07-2020

Matteo Fino (President & PEO)

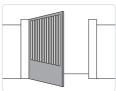
3. Technical specifications

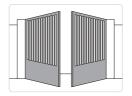
Power supply	230V~ 50Hz						
Power absorption	4A max						
Fuses	F1= F5 A (Motor driver circuits) F2= T3.15 A (Electric lock circuit)						
Motor output	230V AC 50Hz; 2 x 2A max; 1 x 4A max						
Permanent power supply to accessories 0-30	WARNING. the totat sull of the						
Power supply to accessories 0-1	24V=0.3 A max 24V- outputs 30 and 1 must never						
24V~ accessory power supply	24V~ 0.3A max exceed 0.3A.						
Electric lock output	12V~ 15W (max 3s) 12V~ 0.1A (continuous)						
230V~ flashing light output	25W max						
Ambient temperature	-20°C - +55°C						
Storable radio codes	100/200 see RO \rightarrow MU \rightarrow 10/20 (Paragraph 11.5)						
Radio frequency	433.92 MHz (prod. code ZENRS included) or 868.35 MHz (prod. code ZENPRS optional)						
Degree of protection of the container	IP55						
Product size	187x261x103mm						



NOTE: The given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.

3.1 Applications





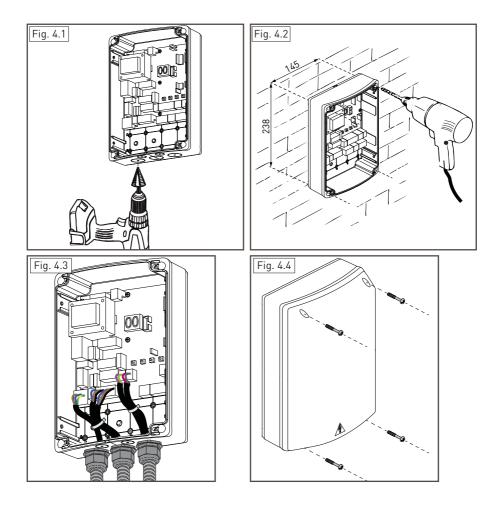
4. Installation and electrical connections

- Perforate the relevant points in the bottom part of the box (Fig. 4.1, page 6).
- Fix the control panel firmly in place. You are advised to use convex head screws (max head Ø 10mm) with a cross imprint (the centre distance for the holes is shown in Fig. 4.2, page 6).
- Insert the cable glands and corrugated tubes from the lower side of the container.
- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cutout upstream of the electrical system.
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the wires have been connected to the terminals.



The connections to the mains power supply and to any possible low voltage wires (230V) in the section outside the control panel must be made on an independent channel separated from the connections to the command and safety devices (SELV = Safety Extra Low Voltage). The corrugated tubes must enter the control panel by a few centimetres via the holes on the base box.

- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains power wires (230V) and the accessory wires (24V) are separated (Fig. 4.3).
- The cables must have dual insulation, be sheathed near the relative connection terminals, and be held in place with ties [B] (not supplied).
- After making the adjustments and settings, fix the cover in place with the screws supplied (Fig. 4.4, page 6).



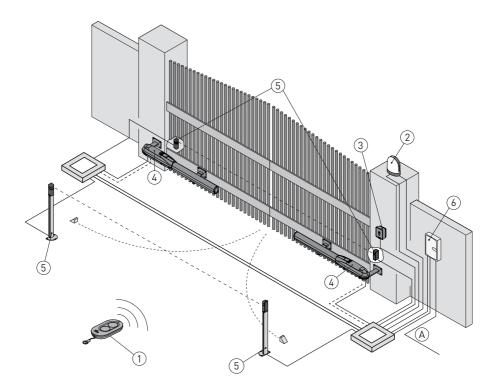
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4.1 Maintenance

The control panel doesn't require any special maintenance.

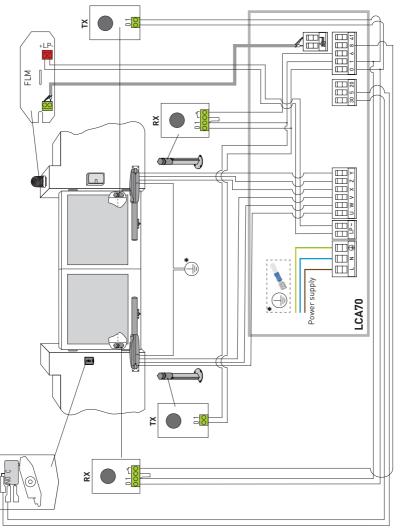
Make regular checks to ensure the seals on the box and the electrical connections are in good condition.

4.2 Standard installation



Ref.	Description	Cable
1	Transmitter	/
	Flashing light	2 x 1mm²
2	Antenna (integrated in the flashing light)	RG-58 coax cable (50Ω)
3	Key selector switch	4 x 0.5mm ²
3	Digital combination wireless keypad	/
4	Actuator (motor)	4 x 1.5mm²
4	Extra low voltage limit switch unit (if present)	3 x 0.5mm²
5	Photocells	4 x 0.5mm²
6	Control panel	3G x 1.5mm²
A	Connect the power supply to a certified-compliant omnipolar switch (not included) with a contact opening distance of at least 3mm. Connection to the mains must be via an independent channel, separated from the connections to the command and safety devices.	

4.3 Standard installation wiring diagram



5. Commands and safety devices

You are advised to read paragraph 11 for all the details about the possible adjustments.



WARNING: terminal 30 (common positive for commands) has the same functions as terminal 1 and for this reason, the commands visible on the display are indicated with 1-5, 1-3, 1-4, etc.



WARNING: make a jumper for all NC contacts if not used, or deactivate them via the relative menu. Terminals with the same number are equal.

5.1 Command inputs

Command		Function	Description
30 5	NO	STEP-BY- STEP	When selecting $\mathbb{B} \subseteq \mathbb{A} \subseteq \mathbb{S} \to \mathbb{I} = \mathbb{S}$, closing the contact starts a sequential opening or closing operation: opening-stop-closing-opening. WARNING : if automatic closure is enabled, the duration of the stop can be defined by selecting $\mathbb{B} \subseteq \mathbb{A} \subseteq \mathbb{S}$. The "opening-stop-closing-opening" sequence can be changed to "opening-stop-closing-stop-opening" by selecting $\mathbb{B} \subseteq \mathbb{A} = \mathbb{P} \mathbb{P}$.
		OPENING	When selecting $\mathbb{B} \subset \mathcal{F} \to \mathcal{F}$, the closure of the contact activates an opening operation.
30 20	NO	PARTIAL APERTURE	The closure of the contact activates a partial opening operation. Once the automation stops, the partial opening control performs the opposite operation to the one performed before the stop.

5.2 Safety inputs

Command		Function	Description
1 <u> t </u>	NC	SAFETY STOP	For safety devices with self-test input: When selecting $PP \rightarrow JB \rightarrow S \Psi$, connect the output contact of the safety device to terminals 1-6 on the control panel (in series with the photocell output contact, if installed).
1 — t 8	NC	Closing safety device	For safety devices with self-test input: When selecting $PP \rightarrow IB \rightarrow S II$, connect the output contact of the safety device to terminals 1-8 on the control panel (in series with the photocell output contact, if installed).
1 - 6 8	NC	CLOSING/OPEN- ING SAFETY DEVICE	For safety devices with self-test input: When selecting $\mathbb{PP} \rightarrow \mathbb{S} \mathbb{H}$, connect the output contact of the safety device to terminals 1-6-8 on the control panel (in series with the photocell output contact, if installed). If $\mathbb{SP} \rightarrow \mathbb{S} \mathbb{H}$, $\mathbb{D} \mathbb{S}$ and \mathbb{DP} cannot be $\mathbb{P} \mathbb{H}$ or $\mathbb{S} \mathbb{H}$.

6. Outputs and accessories

Output	Value of accessories	Description							
<u>\$</u> 24V-	24V~ 0.3A max	AC power supply to accessories Output for power supply to external accessories.							
	+ Accessories power supply 24V = 0.3A max								
	Automation status lamp (configurable) For the operating mode of output 30-13, refer to the selection 3W max 3W max 3W max The current absorbed by the output 13, as well as the absorption of the accessory inserted in the AUX1 is to be counted in tota deliverable from outputs 1 and 30 (300mA).								
	GOPAVRS LAB9 BIXR2	The control panel has two slots for plug-in command and safety boards. The action of the control board can be selected using \mathbb{P} and \mathbb{P} for AUX1. When using slot-in radio boards, remove the RDX module. The display will show $\mathbb{R}V$. WARNING: the plug-in cards must be inserted and removed WARNING: the plug-in cards must be inserted and removed							
AUX 1	BIXPR2 BIXLR42 LAN7S	 with the power supply disconnected. NOTE: the current absorption of the accessories installed in the slots AUX1 if associated with output "1" by the relative jumper, must be considered in the total current deliverable by output 1 (0.3A). Differently if associated to "30" must be considered in the calculation of the total current deliverable by output 30 (0.3A). 							

Output	Value of accessories	Description
	ANTENNA	Input for GOL148REA external antenna or rigid wire antenna supplied according to the operating frequency of the receiver module used.
	230V~ 25W max	230V flashing light For connection of a 230V~ flashing light with auto-flashing function.
	12V~ / 15W (max 3s)	Electric lock It is activated when the operation begins with the automation closed. To modify the operating mode of the LK output, refer to the selection $\mathbb{B} \mathbb{A} \to \mathbb{L} \mathbb{K}$.
E	12V~ / 0.1A (continuous)	
RDX	ZENRS (included) ZENPRS	For installation of a ZENRS (433.92 MHz) or ZENPRS (868.35 MHz) type radio receiver module, purchasable separately. Operation is enabled by selecting $\mathbb{B} \square \to \mathbb{R} \mathbb{M}$. When using slot-in radio boards, remove the RDX module. The display will show $\mathbb{R} \mathcal{V}$.
	(optional)	MARNING: the modules must be inserted and removed with the power supply disconnected.
СОМ	BIXMR2	COM - Enables saving of operating configurations with function $SF \rightarrow SP$. Saved configurations can be recalled with function $SF \rightarrow RE$. The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel.
		WARNING : the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction.

7. Jumper setting

ΈΝ

Jumper	Description	OFF					
JR1	Display mode selection	Display mode The values and parameters present can be only displayed	Maintenance mode The values and parameters present can be displayed and modified. Activated maintenance mode is indicated by the permanent lit on of the right-hand point on the display.				

8. Application examples

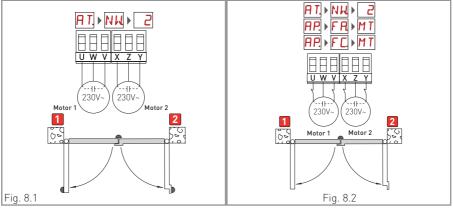


WARNING: make sure that the operating forces of the gate wings comply with the FN12453 standard.

8.1 Automations with two swinging gates



When the Ditec LCA70 control panel is used in applications for automations with two overlapping swinging gate wings, the following connections may be made:

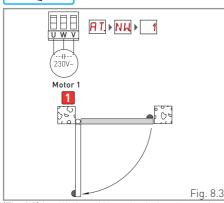


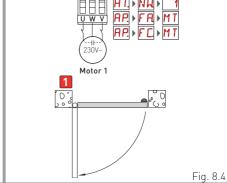
(Fig. 8.1) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches

(Fig. 8.2) Installation with the use of electric limit switches for opening and closure, series connected to the motor's phases.

Automations with one swinging gate wing 8.2

When the Ditec LCA70 control panel is used in applications for automations with one swinging gate wing, the following connections may be made:





AT. NW>

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(Fig. 8.3) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches

(Fig. 8.4) Installation with a mechanical end stop for closure and the use of electric limit switches for opening and closure, series connected to the motor's phases.

9. Using menus

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NOTE: pressure on the keys may be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

9.1 Switching the display ON and OFF

The procedure to switch on the display is as follows: ENTER

- press the key
- the display functioning check starts



• the first level menu is displayed

The procedure to switch off the display is as follows: ESC

• press the key 🍋

NOTE: the display switches off automatically after 60 s of inactivity.

9.2 Navigation keys

- UP and DOWN keys: for scrolling through level one or two menus and through the list of possible values for a specific parameter.
- ENTER key: accesses the next menu level or the list of possible values for a menu parameter. Press and hold to confirm selection of the currently displayed parameter value.
- ESC key: go back to previous step in navigation.
- Simultaneous pressing of the keys UP and ENTER performs an opening command.



• <u>Simultaneous</u> pressing of the keys **DOWN** and **ENTER** performs a closing command.

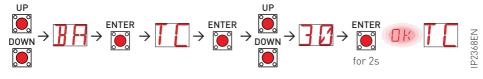


• <u>Simultaneous</u> pressing of the keys **UP** and **DOWN** performs a POWER RESET command. (interruption of the power supply and restart of the automation).

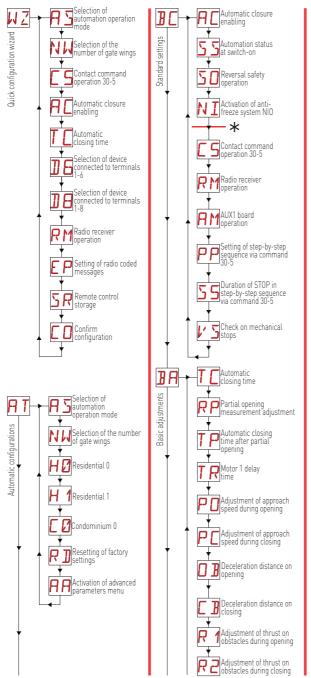


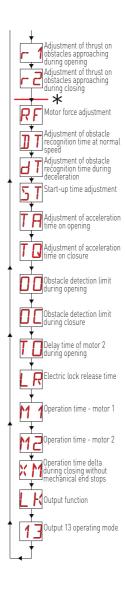
- Hold down the **UP** or **DOWN** key to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

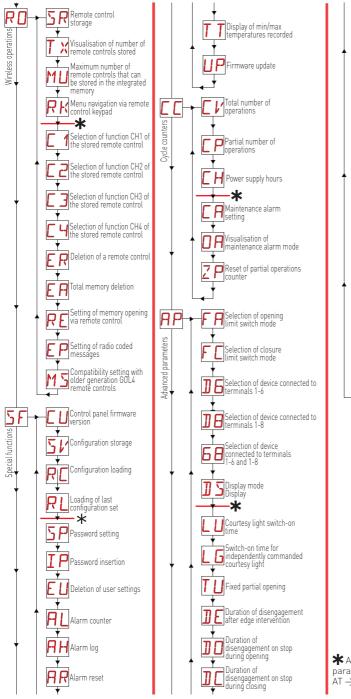
Example: setting of 30 seconds for TC parameter.

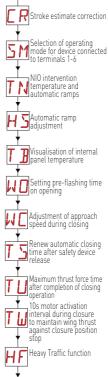


9.3 Menu map











10. Setting up product for first use

Use the WIZARD (WZ) wizard or the level two AT menu (automatic configuration) to set the product up rapidly with a quick configuration procedure [see parag. 11.2].

For detailed, customised configuration, use the main menus **B**C **B**A **RO S**F **C C RP**

10.1 WZ configuration wizard menu

To access the WZ guick configuration wizard menu:

Hold down the ENTER button for 2 seconds. Once the message OK stops flashing, the first menu parameter:

ENTER $\mathbb{W} \xrightarrow{7} \mathbb{P}$ is displayed for 2 sec. (1) $\mathbb{P} \xrightarrow{7} \mathbb{P}$

To set a parameter:

- 1. Press ENTER to access the configuration items.
- 2. Scroll UP/DOWN the possible options.
- 3. To confirm, press the ENTER button for 2 seconds. The selected value flashes and when it has finished, the next parameter appears.



List of parameters in WIZARD menu:

	Display	Description
zard		Description AS - Motor operating mode OO. Automatic operation with deceleration (default) <u>Recommended use</u> : for electromechanical motors installed on gates with unimpeded movement throughout entire stroke, and which use mechanical stops to determine the opening and closing strokes for every operation. Features:
WZ - Quick configuration wizard	A 2	 Peatures: Mechanical stop check function. Deceleration control. Obstacle detection with reversal. Force set at maximum value possible. O1. Automatic operation without deceleration Recommended use: for electromechanical motors installed on gates with impeded movement in proximity of outermost opening and closing positions, and which use mechanical stops to determine the opening and closing strokes for every operation. Features: Mechanical stop check function. Constant speed throughout entire stroke. Obstacle detection with reversal. Force set at maximum value possible. O2. Timed operation with deceleration Recommended use: for electromechanical or hydraulic motors installed on gates with unimpeded movement throughout entire stroke, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun Features: Timed stroke based on M1 and M2 values. Deceleration control. Obstacle detection with reversal. Force set at maximum value possible.

	R	5	 03. Timed operation without deceleration <u>Recommended use</u>: for electromechanical or hydraulic motors installed on gates with impeded movement in proximity of outermost opening and closing positions, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun. <u>Features:</u> Timed stroke based on M1 and M2 values. Constant speed throughout entire stroke. Obstacle detection with reversal. Force set at maximum value possible. 04. Timed operation with force limiting <u>Recommended use</u>: for electromechanical or hydraulic motors installed on particularly problematic gates with impeded movement throughout entire stroke, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun. <u>Features:</u> Timed stroke based on M1 and M2 values. Constant speed throughout entire stroke. Obstacle detection with and m2 values. Features: Timed stroke based on M1 and M2 values. Constant speed throughout entire stroke. Obstacle detection disabled. Reduced force value. WARNING: this operating mode may only be set if the gate is fitted with						
2			self-monitoring safety sensing edges as the obstacle recognition func-						
N N			tion is disabled.						
:	N I	11	NW - Number of wings.						
\geq	IN	KN	1: single wing2: two wings						
D	_	_	C5 - Operation of command associated with contact 30-5						
÷		5	• 1-5: step-by-step (default)						
 Quick configuration wizar 			• 1-3: opening						
Ы	R	E	AC - Enabling of automatic closure ON: enabled (default)						
i,			• OF: disabled						
C	T	_	TC - Setting of automatic closing time [seconds]						
ы С			[NOTE: only viewable visible if AC = ON was selected in previous step]						
\mathbf{X}			 from 0" to 59" with intervals of 1 second. - from <u>1'</u> (default) to 2' with intervals of 10 seconds. 						
. <u></u>			D6 - Selection of device connected to terminals 1-6						
d	Π		• NO: none						
	Ш		• PH: photocells (default)						
Ν	_		For other options, see the specific menu. D8 - Selection of device connected to terminals 1-8						
≥	П		• NO: none						
	<u> </u>	Ы	• PH: photocells (default)						
			For other options, see the specific menu.						
	\square	14	RM - Radio receiver operation • 1-3: step-by-step						
	IN.	11	• <u>1-5</u> : opening (default)						
			EP - AES (Encrypted Packet) reception setting						
			If the possibility to receive coded messages is enabled, the control panel will be compatible						
	L	Γ-	with remote controls of the "ENCRYPTED" type. • ON : enabled						
			• <u>OE</u> : disabled (default)						
			SR - Remote control storage						
	$\overline{\mathbf{V}}$		When you press ENTER, SR starts to flash and you can associate the desired buttons. Once OK is displayed, SR starts to flash again and you can associate the next button. To quit, press						
	J	L <u>v</u>	ESC or ENTER for 2 seconds and go on to the next item.						
			NB: if NO flashes on the display, the remote control may already be stored.						
			CO - Save Wizard settings						
		Π	Here you can save the parameters that have previously been set. • YS: to save and perform a card RESET						
	L	U	 NO: to quit without saving and go back to a blank screen (central part only) 						
			NOTE: the message CO and YS/NO sub-menus flash constantly						

To save the configuration:

In the CO parameter select YS (yes) and press the ENTER button for 2 seconds. After saving, a board POWER RESET cycle is performed automatically:

To quit without saving changes:

Select the option NO for the parameter CO and then press and hold ENTER for 2 seconds

Or: from any main parameter, press the ESC button for 2 seconds. Example:

$E P \rightarrow \bigotimes$ for 2 sec. \mathbb{ND}

NOTES:

- The set values are only stored on the card if they are saved using the CO parameter.
- The parameter CO and the YS/NO options flash constantly.
- After confirming a configuration parameter, the wizard moves on automatically to the next parameter.
- The UP/DOWN buttons may be used at any time, however, to scroll through parameters.
- There is no time limit for selecting and the wizard will not quit automatically.

10.2 Basic example of start-up

NOTE: although this procedure applies to the **"Automatic mode with deceleration"** (AT) → AS= 20), it also serves as a guide for the other modes.



WARNING: the system must have sufficiently robust mechanical end stops or stop limit switches must be installed.



WARNING: if the control panel is used to replace an identical control panel which is faulty, the last automation configuration can be reset by inserting the old control panel storage module into the new control panel and loading the last set configuration using the menu sequence $f \rightarrow RL$.

WARNING: before using the automation, make sure that the operating forces of the gate wings comply with the EN 12453:2017 standard and subsequent revisions.

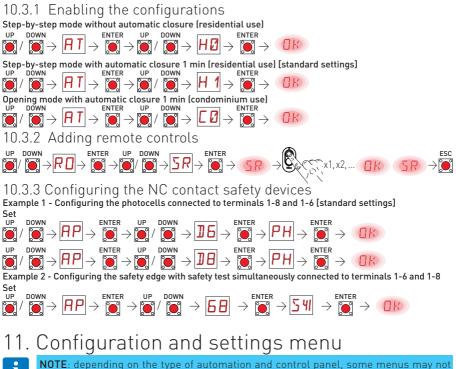
- 1. Turn on the power
- 2. Activate the WZ configuration wizard menu. Set the selections required for the system to be developed.



- 4. With the automation idle in the intermediate position, give an opening command (ENTER + UP keys). Check that the gate wings move in the correct direction. If the direction is not correct, invert the motor phase connections (U-V or X-Y) and repeat the procedure described above. Check that the automation reaches the gate open position and stops against the corresponding mechanical end stops (learning operation).
- 5. Give a closing command (ENTER + DOWN keys) or wait for the automatic closure to intervene if activated and check that the automation performs the corresponding operation by stopping on the mechanical closing end stops (learning operation).
- 6. Connect the safety devices after removing the jumpers 1-6, 1-8, or reactivating the corresponding inputs using the menu parameters $P \rightarrow D$ and $P \rightarrow D$. Make sure the various safety devices are operating correctly.

NOTE: the first closing operation after a power cut or during the learning procedure is carried out with one gate wing at a time.

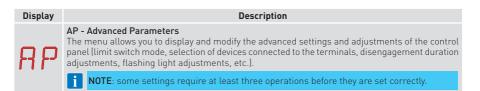
10.3 Frequently used menu sequences



NOTE: depending on the type of automation and control panel, some menus may be available.

11.1 Main menu

WZ - Quick configuration wizard	
🙌 🔟 Quick configuration menu	
AT - Automatic Configuration The menu allows you to manage the automatic configurations of the control panel.	
BC - Basic Configuration The menu allows you to display and modify the main settings of the control panel.	
BA - Basic Adjustments The menu allows you to display and modify the main adjustments of the control panel.	
I NOTE : some settings require at least three operations before they are set correctly	
RO - Radio Operations The menu is used to manage the radio functions of the control panel.	
SF - Special Functions The menu allows you to set the password and manage the special functions in the cont (alarm management, diagnostics enabling, FW updating).	ol panel
CC - Cycle Counter The menu allows you to display the number of operations carried out by the automation manage the maintenance interventions.	tion and



From the main menu you can access the second level menu as follows:

- up DOWN
 use the and and we keys to select the required function;
- press 🚰 to confirm.

After confirming the selection, you access the second level menu.

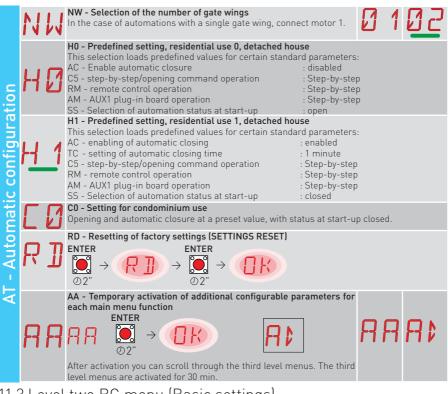
For each function of the main menu, there are also additional configurations that can be viewed by enabling the \overrightarrow{P} function (see the following paragraph). The factory settings for the various second level menu parameters are underlined in green.



NOTE: to check if the parameters have actually been modified, quit the relative parameter and then access it again. The modifications will take effect from the next operation.

11.2 Level two menu - AT (Automatic Configuration)

	Display	Description								Selections available					
AT - Automatic configuration	AS - Motor operating mode • 0. Automatic with deceleration • 0. Automatic with deceleration • • 0. Automatic with deceleration • 0. Obstacle detection with reversal • 0. Maximum force value • • 1. Automatic without deceleration • 0. Obstacle detection with reversal • 0. Maximum force value • 1. Automatic without deceleration • 0. Obstacle detection with reversal • 0. Obstacle detection with reversal • 0. Obstacle detection with deceleration • 0. Obstacle detection with deceleration • 0. Obstacle detection with reversal • Maximum force value • 1. Timed operation with deceleration • 0. Obstacle detection with reversal • Maximum force value • 2. Timed operation without deceleration • Obstacle detection with reversal • Maximum force value • 3. Timed operation without deceleration • Constant speed throughout entire stroke • Obstacle detection with reversal • Maximum force value • Constant speed throughout entire stroke • Obstacle detection with force limiting • Timed stroke based on M1 and M2 values • Constant speed throughout entire stroke • Obstacle detection not activated • Automation tot activated • Constant speed throughout entire stroke • Obstacle detection not activated • Reduced force value • Reduced force value • Neatise if ited with self-mon											1 3			
											r1	r2	RF		
		-									15	15	99		
		1	Automatic without deceleration			-	5		10	10	10	10	99		
									10	10 10	15	15	99		
		3 <u>Timed without deceleration</u> 25 25 5 5 OFF 10									10	10	99		
		4	Timed with force limiting	25	25	5	5	OFF	99	99	99	99	50		



11.3 Level two BC menu (Basic settings)

	Display	Description	Selections available
Basic settings	RC	AC - Enabling of automatic closure OF - Disabled ON - Enabled 1-2 - Dependent on input 30-2	OF <u>ON</u> I- 2
	55	SS - Selection of automation status at start-up OP - Open CL - Closed Indicates how the control panel considers the automation a of switch-on, or after a POWER RESET command.	
	50	S0 - Enabling of reversal safety contact functioning during opening ON - Enabled OF - Disabled When enabled (ON) with the automation idle, if the contact 1-8 is open, all oper- ations are prevented. When disabled (OF) with the automation idle, if the contact 1-8 is open, opening operations are permitted.	
BC -	NI	NI - Enabling of NIO electronic anti-freeze system ON - Enabled OF - Disabled When enabled (ON), it maintains the efficiency of the motor even at low Image:	exposed to the same y selecting $PP \rightarrow TN$. IVAC (LP) flashing light be used when motors

11.3.1 Additional configurable BC level parameters available with \square \square \square enabled

	Display	Description	Selec avail	
	٢٥	C5 - Step-by-step/opening operation via 1-5 command (wakeup from stand-by) 1-3 - Opening 1-5 - Step-by-step LG - Courtesy light command	I- 3 N D	-5 5
S		NO - Input 5 disabled		
b	RM	RM - Radio receiver operation 1-3 - Opening 1-5 - Step-by-step	1-3	1-5
asic settii	RM	AM - Step-by-step/opening operation via command from AUX1 board 1-3 - Opening 1-5 - Step-by-step NO - Disabled	- 3 N 0	<u> - 5</u>
BC - Ba:	РP	PP - Setting of step-by-step sequence via command 30-5 ON - Opening-Stop-Closing-Stop-Opening OF - Opening-Stop-Closing-Opening	ΠN	<u>DF</u>
	55	 S5 - Duration of STOP in step-by-step sequence via command 30-5 ON - Permanent (automatic closure is excluded until a new command is given) OF - Temporary (the automatic closure timer intervenes, if enabled) 	0N	<u>OF</u>
	V 5	VS - Checking of mechanical end stops When enabled (ON), with every power supply connection, the automation automatically checks the mechanical opening and closing end stops/ stop limit switches. During the learning operation, the display shows the message MO and the closing operation involves one gate wing at a time (1).	<u>0 N</u>	0F

11.4 Level two BA menu (Basic adjustments)

NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

BA	Display	Description	Selections available
	ΤC	TC - Setting of automatic closing time [s] It is set with different intervals of sensitivity. from 0" to 59" with intervals of 1 second; from 1' to 2' with intervals of 10 seconds.	2 2 5 9 1 1 1 2 1 1 1 1 1 1 1 1 1 1
	RP	RP - Adjustment of partial opening measurement [%] Adjusts the percentage of operation in relation to the total opening of the automation. Partial opening is performed on gate wing 1. 10 - Minimum 99 - Maximum	
	ΤP	TP - Setting of automatic closing time after partial opening [s] It is set with different intervals of sensitivity. from 0" to 59" with intervals of 1 second; from 1' to 2' with intervals of 10 seconds.	00 ,59 ' <u></u> 2'

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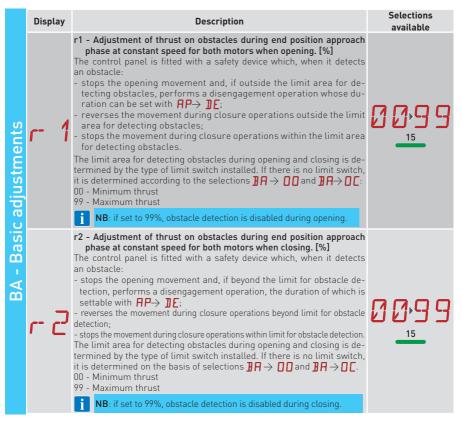
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	Dis	play	Description	Selections available
	T	R	TR - Motor delay time [s] Delay time for closure of gate wing 1 in relation to gate wing 2. 00 - 30s	
	Ρ		PO - Adjustment of approach speed during opening Indicates the speed from the end of the deceleration ramp to the end of the opening stroke 10 - Minimum 25 - Maximum	10 ^{,2} 5
	Ρ	Ε	PC - Adjustment of approach speed during closing Indicates the speed from the end of the deceleration ramp to the end of the closing stroke. 10 - Minimum 25 - Maximum	
	0	B	OB - Setting of deceleration/braking time during opening [s] Indicates the time between the start of the deceleration ramp and the end of the opening stroke 1 - Minimum 30 - Maximum	
nents	Ε	B	 OB - Setting of deceleration/braking time during closing [s] Indicates the time between the start of the deceleration ramp and the end of the closing stroke 1 - Minimum 30 - Maximum 	
BA - Basic adjustments	R	1	 R1 - Adjustment of thrust on obstacles during normal operation at constant speed for both motors when opening. [%] The control panel is fitted with a safety device which, when it detects an obstacle: stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with <i>PP</i>→ <i>DE</i>: reverses the movement during closure operations outside the limit area for detecting obstacles; stops the movement during closure operations within the limit area for detecting obstacles. The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selections <i>DP</i>→ <i>DC</i>: 00 - Minimum thrust NB: if set to 99%, obstacle detection is disabled during opening. 	Ø Ø,9 9
	R	2	 R2 - Adjustment of thrust on obstacles during normal movement at constant speed for both motors when closing. [%] The control panel is fitted with a safety device which, when it detects an obstacle: stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with AP→ JE: reverses the movement during closure operations outside the limit area for detecting obstacles; stops the movement during closure operations within the limit area for detecting obstacles. The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selections JA → O and JA → O : 00 - Minimum thrust NB: if set to 99%, obstacle detection is disabled during closing. 	Ø Ø 9 9

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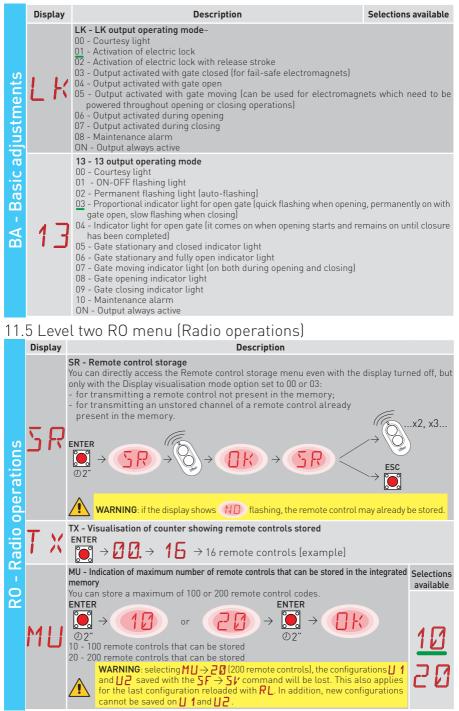


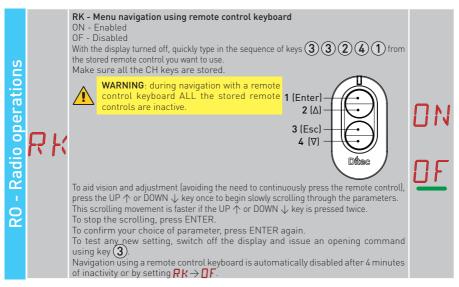
11.4.1 Additional BA level parameters that can be configured (available with R T → R R enabled)

NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

BA - Basic adjustments	Display	Description	Selections available
	RF	RF - Motor force adjustment. [%] Enabled only during operations in which sensitivity R1, R2, r1 or r2 is set to 99%	20,99
]] T	DT - Adjustment of obstacle recognition time at normal speed. [s/100] 20 - Minimum 99 - Maximum	
	dТ	dT - Adjustment of obstacle recognition time during deceleration. [s/100] 20 - Minimum 99 - Maximum	
	5 T	ST - Adjustment of start time [s] During start-up, obstacle detection is disabled. 2.0 - Minimum 3.0 - Maximum	2.0

	Display	Description	Selections available
	TR	TA - Adjustment of acceleration time during opening [s] 0.5 - Minimum 1.5 - Maximum	Ø.5, 1.5
	T Q	TQ - Adjustment of acceleration time during closing [s] 0.5 - Minimum 1.5 - Maximum	0.5, 1.5
	00	OO - Obstacle detection limit during opening [%] Indicates the percentage of the distance travelled during $\mathbb{R} \to \mathbb{O}$ in which disengagement is deactivated.	
	00	OC - Obstacle detection limit during closing [%] Indicates the percentage of the distance travelled during $\mathbb{B} \mathbb{A} \rightarrow []$ in which reversal is deactivated.	05 <u>9</u> 9
ents	TO	TO - Setting motor 2 opening delay time [s] Adjustment, in seconds, of the delay time for starting the operation of motor 2, in relation to motor 1.	
 Basic adjustments 	LR	LR - Electric lock release time [s] If enabled, this indicates the electric lock activation time at the start of every opening operation with the automation closed.	0.5°C.5
sic adj		M1 - Operation time - motor 1 [s] Adjustment, in seconds, of the total operation time for motor 1. 02 - Minimum 99 - Maximum	02,99
m	M 1	WARNING : it is set with a sensitivity interval of 0.5s, shown when the decimal point on the right lights up.	
₫Ъ		Example: 🖸 🧻 = 7 seconds / 🚺 🗍 = 7.5 seconds	
		NOTE: the setting of M_1 is only active with $\mathbb{B} \square \to V \square \to \square F$.	
		M2 - Operation time - motor 2 [s] Adjustment, in seconds, of the total operation time for motor 2. 02 - Minimum 99 - Maximum	
	M2	WARNING : it is set with a sensitivity interval of 0.5s, shown when the decimal point on the right lights up.	
		Example: 🚺 🧻 = 7 seconds / 🚺 🗍 = 7.5 seconds	
		NOTE : the setting of M^2 is only active with $\mathbb{B} \square \to \mathcal{V} \ \mathbb{S} \to \mathbb{O} \mathcal{F}$.	
	хM	 XM - Variation in time during closing without mechanical end stops. [s] Variation in time to be added to M1 and M2 during closing. 00 - Minimum 30 - Maximum 	
	хT	XT - Variation in operation time when reversing. [s] Variation in time to be added to OB and CB. 00 - Minimum 30 - Maximum	



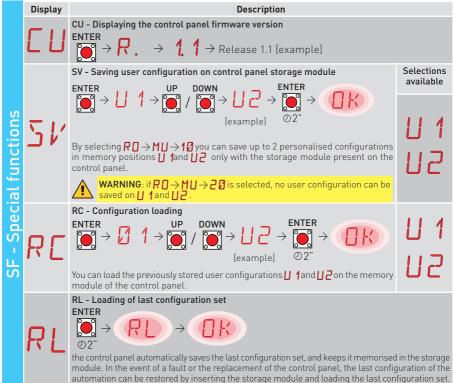


11.5.1 Additional configurable BO level parameters available with \square \square \square enabled

	Display	Description	Selections available
1 - Radio operations	C 1 C 2 C 3 C 4	C1, C2, C3, C4 - Selection of CH1, CH2, CH3, CH4 function of stored remote control N0 - No setting selected 1-3 - Opening command 1-4 - Closing command 1-5 - Step-by-step command P3 - Partial opening command LG - Command to switch the courtesy light on/off 1-9 - STOP command If even just one (any) CH key of the remote control is stored, the opening or step- by-step command is implemented. NOTE: the <i>J</i> = 3 (opening) and <i>J</i> = 5 (step-by-step) options are available as alternatives, and depend on the selection 3 [_ → R M. If 2-4 CH keys of a single remote control are stored, the functions matched in the factory with the CH keys are as follows: • CH1 = opening/step-by-step command; <i>I</i> = 3 , <i>I</i> = 5 (depending on parameter R M): • CH2 = partial opening command; P 3 : • CH3 = command to switch on/off the courtesy light; <u>L</u> <u>6</u>	N [] - 3 - 4 - 5 - 5 L [] - 9
RO	ER	ER - Deletion of a single remote control ENTER $\bigcirc 2^n$ \rightarrow \bigcirc	
	ER	EA - Total deletion of part of storage used for remote controls ENTER \bigcirc 2" \rightarrow \bigcirc 2" \rightarrow 0"	

	Display	Description	Selections available
	RE	RE - Setting memory opening from remote control OF - Disabled ON - Enabled When enabled (ON), the remote programming is activated. To store new remote controls without using the control panel, refer to the remote control instructions.	
		NOTE : make sure you do not accidentally memorise unwanted remote controls.	
RO	EP	EP - Setting coded messages If the possibility to receive coded messages is enabled, the control panel will be compatible with remote controls of the "ENCRYPTED" type.	OF ON
		MS - Backward compatibility setting with older generation GOL4 remote controls.	
		NOTE : firmware version 2.2.8 or higher is required.	
	МЪ	 OF - Compatibility with old generation GOL4 and new ZEN remote controls. ON - Compatibility with ZEN series remote controls NOTE: MS=0N is recommended if only ZEN series remote controls are used on the system. 	<u><u>D</u>N</u>

11.6 Second level menu - SF (Special Functions)



11.6.1 Additional configurable SF level parameters available with \blacksquare \intercal \rightarrow \blacksquare \blacksquare enabled

	Disp		Description	
			SP - Setting the password	
	5		$\underbrace{ENTER}_{[example]} \rightarrow \boxed{1} \rightarrow \underbrace{UP}_{[example]} / \underbrace{DOWN}_{[example]} \rightarrow \underbrace{ENTER}_{[o 2'']} \rightarrow \underbrace{UP}_{[o 2'']} \rightarrow UP$	
			i NOTE: this can only be selected when the password is not set.	
			Setting the password prevents unauthorised personnel from accessing selections and adjustments. You can delete the set password by selecting the sequence JR1=0N, JR1=0FF, JR1=0N, IR1=0N, IR	
	T	- p	$ \begin{array}{c} \text{IP - Inserting the password} \\ \text{ENTER} \\ \hline \end{array} \rightarrow \begin{array}{c} \text{UP} \\ \hline \end{array} & 1 \end{array} \rightarrow \begin{array}{c} \text{DOWN} \\ \hline \end{array} \rightarrow \begin{array}{c} \text{DOWN} \\ \hline \end{array} \rightarrow \begin{array}{c} \text{ENTER} \\ \hline \end{array} \rightarrow \begin{array}{c} \text{OP} \\ \hline \end{array} \end{pmatrix} $	
	<u> </u>		I NOTE: this can only be selected when the password is set.	
			When the password is not inserted, you can access the display mode regardless of the selection made with JR1. When the password is inserted, you can access in maintenance mode.	
S			EU - Deletion of user configurations and last configuration set (can be called up from R []	
Special functions	Ε	[]]	$\overbrace{02^{"}}^{\text{ENTER}} \rightarrow \overbrace{22^{"}}^{\text{ENTER}} \rightarrow \overbrace{02^{"}}^{\text{ENTER}} \rightarrow \overbrace{02^{"}}^{\text{ENTER}}$	
L f			AL - Alarm counter	
ecia	Used to view, in sequence, the counters of alarms that have been triggered at least or code + number of times triggered). With UP and DOWN, you can scroll through all the counters and see all the alarms			
SF - Sp	R	┝┥	AH - Alarm log Used to view, in sequence, alarms that have been triggered (up to a maximum of 20). With UP and DOWN, you can scroll through the entire alarm log. The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number (0) corre- sponds to the oldest alarm.	
			AR - Alarm reset Resets all the alarms in the memory (counters and log).	
			ENTER	
	R	R	$\bigotimes_{02^{''}} \rightarrow \bigcup_{02^{''}} \bigotimes_{02^{''}} \bigotimes_{02^{'''}} \bigotimes_{02^{''}} \bigotimes_{02^{'''}} \bigotimes_{02^{'''}} \bigotimes_{02^{'''}} \bigotimes_{02^{'''}} \bigotimes_{02^{'''}} \bigotimes_{02^{'$	
			NOTE : when the installation has been completed, you are advised to delete the alarms in order to facilitate future checks.	
	T	T	TT - Display of min/max temperatures recorded - press for 2 sec to reset the values; - minimum value with active right decimal point.	
		р	UP - Firmware update Activates the card bootloader in order to update the firmware. ENTER	
		•	©2"	

11.7 Second level menu - CC (Cycles Counter)



11.7.1 Additional configurable CC level parameters available with \square \square \square enabled

	Display	Description Selections available
CC - Cycle counters	C A	CA - Setting the maintenance alarm (factory setting - alarm deactivated: 0.0 00. 00) You can set the required number of operations (regarding the partial operations counter) for signalling the maintenance alarm. When the set number of operations is reached, the alarm message appears on the display / \mathcal{D} . Example: Setting the maintenance alarm after 700 operations (00) (07) (00) ENTER $\mathcal{D} \rightarrow \mathcal{D} \rightarrow $
	0 A	 OA - Selecting maintenance alarm display mode 00 - Visualisation on display (alarm message 1/ 0) 01 - Visualisation on flashing light (with the automation idle, 4 flashes are made and then repeated every hour) and on display (alarm message 1/ 0). 02 - Visualisation on "open gate" indicator light (with the automation closed, 4 flashes are made and then repeated every hour) and on display (alarm message 1/ 0).
	ZP	ZP - Reset of partial operations counter ENTER @? @?" For correct functioning, you are advised to reset the partial operations counter: - after maintenance work; - after setting the maintenance alarm interval.

11.8 Level two AP menu (Advanced parameters)

	Display	Description	Selections available
AP - Advanced parameters	FR	FA - Motor 1 and 2 opening limit switch mode NO: no limit switch (timed operation or with detection of stop) MT: stop limit switch series connected to the motor phase	ND MT
	FΕ	FC - Motor 1 and 2 closing limit switch mode NO: no limit switch (timed operation or with detection of stop) MT: stop limit switch series connected to the motor phase	ND MT
]6	$\begin{array}{l} D6 \mbox{-} \mbox{Selection of device connected to terminals 1-6} \\ N0 \mbox{-} \ None \\ SE \mbox{-} \ Safety sensing edge (if contact 1-6 opens, 10 cm disengagement is implemented after stop). \\ S41 \mbox{-} \ Safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection \begin{array{c} PP \mbox{-} \mbox{JE} \end{tabular} \\ PH \mbox{-} \mbox{Photocells} \\ P41 \mbox{-} \mbox{Photocells with safety test} \end{array}$	N
]8	D8 - Selection of device connected to terminals 1-8 NO - None SE - Safety edge S41 - Safety edge with safety test PH - Photocells P41 - Photocells with safety test	
	68	 68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8 NO - None SE - Safety edge S41 - Safety edge with safety test If different from NO, the simultaneous opening of inputs 1-6 and 1-8 causes: movement stop and reversal during a closing operation. movement stop and disengagement of a duration depending on the selection P→JE during an opening operation. 	NO SE SH
	15	 DS - Setting of display visualisation mode without alarm 00 - No information displayed. 01 - Countdown to automatic closure displayed. 02 - Automation status (see paragraph 13.1). 03 - Commands and safety devices (see paragraph 13.2). i) NOTE: the setting i 1 allows you to see when a radio transmission is received, for range checks. 	

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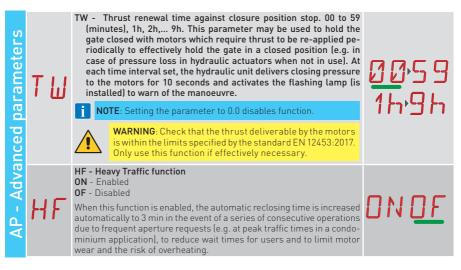
11.8.1 Additional configurable AP level parameters available with A T → A A enabled



	5	М	 SM - Selection of operating mode of device connected to terminals 1-6 OD - During opening operation, open state of safety contact stops movement (with disengagement if □ 6 → 5 € / 5 ៕). OI - During opening operation, open state of safety contact stops movement (with disengagement if □ 6 → 5 € / 5 ៕). The interrupted operation is resumed when the contact is closed again. O2 - During opening operation, open state of safety contact stops movement (with disengagement if □ 6 → 5 € / 5 ៕). The interrupted operation is resumed when the contact is closed again. O2 - During closing operation, open state of safety contact stops movement (with disengagement if □ 6 → 5 € / 5 ៕). An opening operation is performed when the contact is closed again. O3 - During closing operation, open state of safety contact stops movement. During the opening operation, the safety device is ignored. O4 - During openation, the safety device is closed again. During the closing operation, the safety device is closed again. During the closing operation, open state of safety contact stops movement (with disengagement if □ 6 → 5 € / 5 ៕). The interrupted opening operation, the safety device is closed again. During the closing operation, the safety device is ignored. O5 - During closing operation, open state of safety contact stops and then reverses movement. During the opening operation, the safety contact stops and then reverses movement. During the opening operation, the opening	-	0 1 0 3 0 5
meter	T	N	TN - Setting of intervention temperature for the NIO electronic an- ti-freeze system and automatic HS ramps [°C] This value does not refer to the ambient temperature, but to the internal control panel temperature.	- 9	20
AP - Advanced parameters	Н	5	 HS - Automatic ramp adjustment ON - Enabled OF - Disabled When enabled (ON), at low ambient temperatures the start time 5 T increases up to the maximum value and the acceleration time T A and T and	٥N	<u>DF</u>
P - A	T	B	TB - Permanent display of the internal control panel temperature [°C]	ΠN	<u>DF</u>
A	IJ		 WO - Setting of pre-flashing time on opening [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the opening operation from a voluntary command. 00 - Minimum 05 - Maximum. 		5
	11	E	WC - Setting of pre-flashing time on closing [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the closing operation from a voluntary command. 00 - Minimum 05 - Maximum.		5
	T	5	TS - Setting of renewal of automatic closing time after safety device release [%] 00 - Minimum 99 - Maximum.		<u>9</u> 9
	T	U	TU - Time at maximum thrust force after completion of closing operation (e.g. to relatch electric lock) - 0.0 to 9.9s Image: NOTE: Setting the parameter to 0.0 disables thrust.	0.0	9.9

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12. Diagnostics

12.1 Data Logging integrated in the board

The Ditec LCA70 control panel is equipped with an internal system which allows the installer to check whether any alarms have been triggered, see how many times each alarm has been triggered and view a the log of the last twenty alarms.

12.1.1 Alarm counter

With the third level menus enabled ($PT \rightarrow PR$), go to $SF \rightarrow PL$ to see all the alarms recorded by the control panel. The display alternately shows the alarm code and the number of times it was triggered.

Use the 💓 and 💓 keys to scroll through the entire list of alarm counters.

12.1.2 Alarm log

With the third level menus enabled ($AT \rightarrow AA$), go to $5F \rightarrow AH$ to see the alarm log (the last 20 alarms recorded). The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number corresponds to the oldest alarm.

Example: - 1 _ 0]] _ - 1 _ 0]] _

```
UP DOWN
Use and to scroll through the alarm log.
```

13. Signals visualised on the display



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NOTE: depending on the type of automation and control panel, certain visualisations may not be available.

13.1 Display of automation status

 $\ensuremath{\text{NOTE}}$: the automation status display mode is only visible with Display visualisation mode set to 02.

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Display	Description	Display	Description
	Automation closed	10	Automation opening
	Automation open] 1	Automation closing, from partial opening
	Automation stopped in intermediate position	31	Automation in partial opening
b 1	Automation closing]1	Automation partially open

13.2 Display of safety devices and commands

i

NOTE: the safety device and command display mode is only visible with Display visualisation mode set at 01 or 03.

AP > 15 > 0 1 AP > 15 > 0 3

Display	Description	Display	Description
1-2	1-2 - Automatic closure enable command.	5.2.	S.2. - Stop detection during aperture oper- ation - motor 2.
1-3	1-3 - Opening command.		00. - Obstacle detection limit reached dur- ing aperture operation - motor 1.
1-5	1-5 - Step-by-step command.	0.0.	00. - Obstacle detection limit reached during aperture operation - motor 2.
1-6	1-6 - Safety device with opening and closing stop.	DC.	00. - Obstacle detection limit reached during closure operation - motor 1.
1-8	1-8 - Safety device with reversal during closing operation.	D.C.	00. - Obstacle detection limit reached during closure operation - motor 2.
68	68 - Device connected simultaneously to terminals 1-6 and 1-8.	RV	RV - Enable/disable built-in radio receiver via RDX.
PЗ	P3 - Partial opening command.	MIJ	MQ - Mechanical end stop learning opera- tion in progress.
R×	RX - Radio reception (from any memorised key of a transmitter stored in memory)	HT	HT - Motor heating (NIO function) in progress.
N×	NX - Radio reception (from any non-memorised key) NOTE : with the selection $PP \rightarrow J S \rightarrow J$, it is also visualised when a command is received from a non-stored transmitter.	J 1 РГ	JR1 - Change in jumper JR1 status. PC - Connected HOST (Personal Computer) recognised.
Ε×	EX - Rolling-code radio reception out of sequence	ΕS	ES - Switch to Green Mode (energy-saving)
ĒP	EP - Radio reception not compliant with parameter configuration $\mathbb{P} \bigcirc \mathbb{P} \mathbb{P}$	1E	1C - Closing operation (1 gate wing at a time)
EX	CX - Command received from AUX1 board	LG	LG - Courtesy light/garden light command
51	S1. - Stop detection during closure oper- ation - motor 1.	HD	H0 - Pressure hold function activation for hydraulic pistons
5. 1.	S.1. - Stop detection during closure oper- ation - motor 2.	HS	HS - Activation of increased thrust force function in closure operation
52.	S2 Stop detection during aperture oper- ation - motor 1.		

13.3 Visualisation of alarms and faults



WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

Type of alarm	Display	Description	Operation
	MC - Motor 2 not detected during operation		Check the motor 1 connection and if the thermal switch has tripped.
			Check the motor 2 connection and if the thermal switch has tripped.
_	MH	MH - Gate wing overlap incorrect	Check that the motor which is the first to make the opening (M1) is connected as shown in fig. 1.
Mechanical alarm	ΜI	MI - Detection of fifth consecutive obstacle	Check for the presence of permanent ob- stacles along the stroke of the automation. Check the settings / operating of any limit switches.
Mecha	Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system Image: Second system		Check for the presence of obstacles along the automation stroke.
	30	OE - Obstacle on wing 1 detected during closure.	Check for the presence of obstacles along the automation stroke.
	٥F	OF - Obstacle on wing 2 detected during aperture.	Check for the presence of obstacles along the automation stroke.
	06	OG - Obstacle on wing 2 detected during closure.	Check for the presence of obstacles along the automation stroke.
Settings alarm	56	S6 - Incorrect setting of safety device test	Check the configuration of parameters $\mathbb{J}_{6}^{\mathbb{C}}$, $\mathbb{J}_{6}^{\mathbb{C}}$, $\mathbb{J}_{6}^{\mathbb{C}}$, $\mathbb{J}_{6}^{\mathbb{C}}$, $\mathbb{J}_{6}^{\mathbb{C}}$ and $\mathbb{J}_{6}^{\mathbb{C}}$ cannot be \mathbb{P} 4/ or \mathbb{S} 4/.
Service alarm	ľØ	VO - Maintenance request.	Proceed with the scheduled maintenance intervention.

Type of alarm	Display	Description	Operation			
	IS	I5 - No voltage 0-30 (faulty voltage regulator or short-circuit on accessories)	Check there is no short circuit in connection 0-30. If the problem persists, replace the control panel.			
	I6	<pre>I6 - Excessive voltage 0-30 (faulty voltage regulator)</pre>	Replace the control panel.			
	I٦	17 - Internal parameter error - value out- side limits	Reset. If the problem persists, replace the control panel.			
	I8	18 - Program sequence error	Reset. If the problem persists, replace the control panel.			
	IR	IA - Internal parameter error (EEPROM/ FLASH)	Reset. If the problem persists, replace the control panel.			
alarm	IB	IB - Internal parameter error (RAM)	Reset. If the problem persists, replace the control panel.			
Internal control panel alarm	IC	IC - Operation time out error (>3 min).	Manually check that the gate wing moves freely. If the problem persists, replace the control panel.			
al contro	ΙE	IE - Power supply circuit fault	Reset. If the problem persists, replace the control panel.			
Interné	IM	IM - TRIAC alarm - motor 1 short circuited or always ON.	Reset. Check the settings / operating of any limit switches. If the problem persists, replace the control panel.			
	IN	IN - TRIAC alarm - motor 2 short circuited or always ON.	Reset. If the problem persists, replace the control panel.			
	IU	$\ensuremath{\text{IU}}$ - Motor 1 voltage reading circuit test error.	Reset. If the problem persists, replace the control panel.			
	IV	$\ensuremath{\text{IV}}$ - Motor 2 voltage reading circuit test error.	Reset. If the problem persists, replace the control panel.			
	ХХ	UP DOWN XX - Firmware reset commanded by simultaneous usage + • keys				
	NJ	WD - Firmware reset not commanded				
Radio operations alarm	RØ	R0 - Storage module installed containing over 100 stored remote controls. WARNING: the $\square \rightarrow \square \rightarrow 2 \square$ setting is made automatically.	To save the system configurations on the storage module, delete any stored remote controls and bring the total to less than 100. Set $\mathbb{R} \supseteq \rightarrow \mathbb{N} \sqcup \rightarrow 1\mathbb{D}$.			
	RJ	R3 - Storage module not detected	Insert a storage module.			
	RЧ	R4 - Storage module not compatible with the control panel	Insert a compatible storage module.			
	RS	${\bf R5}$ - No serial communication with the storage module	Replace the storage module.			
	R6	R6 - Specific storage module for testing installed.				
Power supply alarm	P 1	P1 - Microcontroller voltage too low.	Check the control panel is powered cor- rectly.			

Type of alarm	Display	Description	Operation
E	R 🛛	A0 - Test of safety sensor on contact 6 failed.	Check the safety device is working properly.
			If the supplementary safety board is not inserted, check the safety test is disabled.
Accessories alarm	日 1	A1 - Test of safety sensor connected simul- taneously to contacts 6 and 8 failed.	Check the wiring and correct operation of the safety sensor.
Accessor	83	A3 - Test of safety sensor on contact 8 failed.	Check the safety device is working properly.
			If the supplementary safety board is not inserted, check the safety test is disabled.
	RB	AB - Overload on output 30-13	Check the device connected to output 30-13 is working properly.

14. Troubleshooting

Problem	Possible cause	Alarm s	ignalling	Operation
The control panel does not switch	No power supply.			Check the power supply cable and the F1 fuse.
on	Internal fault			Contact Technical Service
	No power.			Check the power supply cable and the F1 fuse.
	Short circuited accessories.	IS		Disconnect all accessories from ter- minals 0-1 or 0-30 (a voltage of 24V= must be present) and reconnect them one at a time. Contact Technical Support Service
	Blown line fuse.			Replace fuse F1.
	Safety contacts are open.	1-6 68	1-8	Check that the safety contacts are closed correctly (NC).
The automation does not open or close	Safety contacts not correctly connected or self-controlled safety edge not functioning correctly.	AØ A 1 A 3	- 6 - 8 6 8	Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge.
	Photocells activated.	1-6	1-8	Check that the photocells are clean and operating correctly.
	The safety edges connected to 6R and 8R are pressed or blocked	6 <i>R</i>	BR	Check the resistance values of the safety edges.
	The automatic closure does not work.			Issue any command. If the problem per- sists, contact Technical Service
	Faulty motor or tripping of thermal switch.	M B M E		Check motor connection, if the problem persists, contact Technical Service.
External safety devices not acti- vating	Incorrect connections between the photocells and the control panel.			Check that I- 6 / I- 8 is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board.
				Check the $\texttt{PP} \rightarrow \texttt{J6}$ and $\texttt{PP} \rightarrow \texttt{J8}$ setting

Problem Possible cause Alar		Alarm signalling	Operation
The automation opens/closes briefly and then stops.	There is a presence of friction.	MI 0] 0E 0F 0G	Manually check that the automation moves freely and check the R 1/ R 2 adjustment. Check that the limit switches, if installed, are working correctly Contact Technical Service
has limited range	The radio transmission is im- peded by metal structures and reinforced concrete walls.		Install the antenna outside. Replace the transmitter batteries.
The remote control does not work	No storage module or incorrect storage module.	R Ø R 3 R 5	Switch the automation off and plug in the correct storage module. Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module.

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Entrematic Group AB Lodjursgatan 10 SE-261 44, Landskrona Sweden www.entrematic.com